



# Revisiting Parameter Synthesis for One-Counter Automata

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OFCOURSE talk series, MPI-SWS, Germany



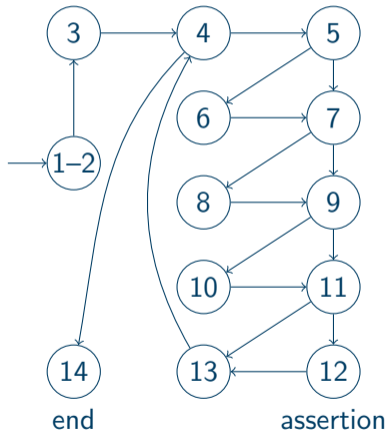
## Using the control flow graph

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1 x = 0
2 i = 0
3 i += x
4 while i >= 0:
5     if i == 0:
6         print("Hello world!")
7     if i == 1:
8         print("Lockdown = pain")
9     if i == 2:
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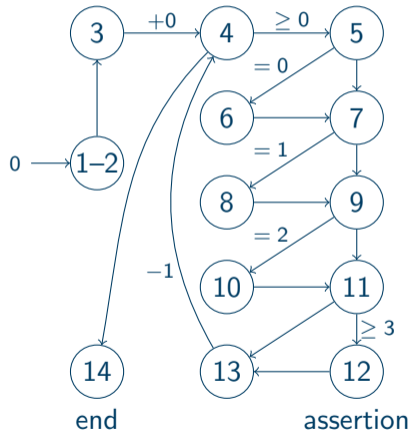
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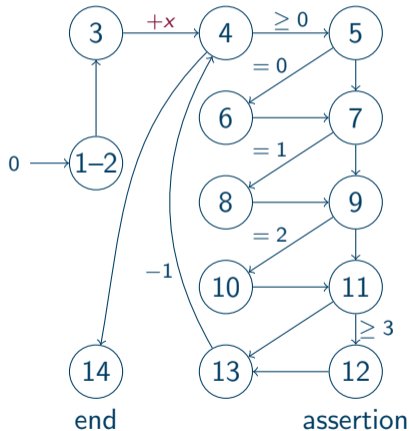
## Parametric one-counter automata

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# Outline

Synthesis Problems for One-Counter Automata

Presburger Arithmetic with Divisibility

Encoding Synthesis Problems into PAD

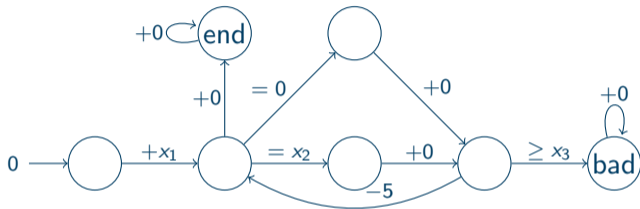
Going back to logic: BIL



# Parametric One-Counter Automata

Natural-valued parameters

$$X = \{x_1, \dots, x_n\}$$



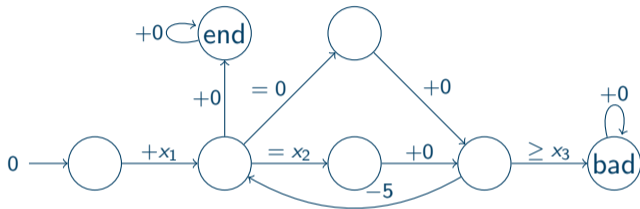




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Succinct OCA with Parameters

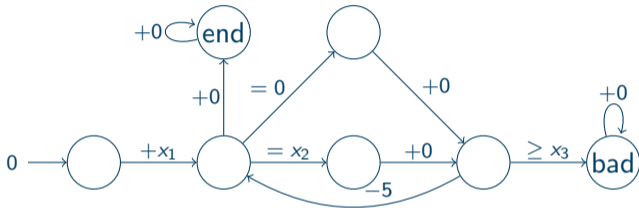
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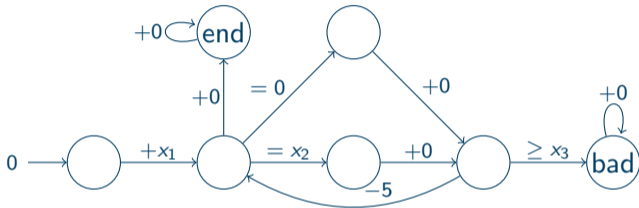
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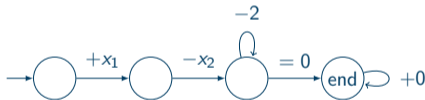
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## Definition (Parameter-value synthesis)

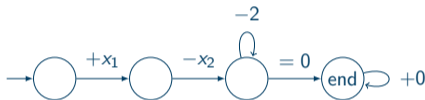
Is there some valuation  $V : X \rightarrow \mathbb{N}$  such that all (infinite) runs of  $\mathcal{A}$  satisfy a given  $\omega$ -regular property?



	LTL	Reachability	Safety	Büchi	coBüchi
Lower bound	<b>PSPACE</b> -hard	<b>coNP</b> -hard	—	<b>NP<sup>NP</sup></b> -hard	—
Upper bound	in <b>N3EXP</b>	— in <b>N2EXP</b> —			



## Haase-Lechner approach via Logic



Logical formula:  $x_1 \geq 0 \wedge x_1 \geq x_2 \wedge 2|x_1 - x_2$

*Presburger Arithmetic with divisibility!*



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Theorem (Lipshitz'78, Lechner-Ouaknine-Worrell'15)

*The existential fragment of PAD (EPAD) is decidable and in **NEXP**.*



## Restriction: $\forall\exists_R$ PAD

- ▶  $\forall\exists_R$ PAD =  $\forall x_1 \dots \forall x_n \exists y_1 \dots \exists y_m \cdot \varphi(\mathbf{x}, \mathbf{y})$ 
  - ▶ in  $\varphi$ , divisibilities of the form  $f(\mathbf{x}) \mid g(\mathbf{x}, \mathbf{y})$



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- ▶  $\forall\exists_R$ PAD<sup>+</sup> =  $\forall\exists_R$ PAD with  $\neg$  not allowed before divisibility
  - ▶ A negation normal form where  $\mid$  cannot be negated



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Claim (Bozga-Iosif'05, Lechner'15)

The synthesis problems for SOCAP are decidable via an encoding into  $\forall\exists_R\text{PAD}^+$ .



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# Encoding chronology

What we need?

Formulas  $\varphi(\mathbf{x})$  such that  $V : X \rightarrow \mathbb{N}$  satisfies  $\varphi$  iff  $\mathcal{A}$  has a  $V$ -run reaching  $t$  from  $s$ .



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## Theorem (Haase et. al. '09)

*If  $(q, c) \rightsquigarrow (q', c')$  without zero-test, then  $(q, c) \xrightarrow{\pi_1 \pi_2 \pi_3}$  such that,  $\pi_1, \pi_2$  and  $\pi_3$  are type 1, type 2 and type 3 reachability certificates.*



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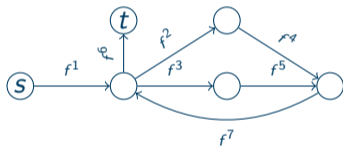
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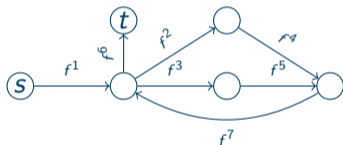


$$\bigwedge_{q \notin \{s, t\}} \left( \sum_{p \in T(\cdot, q)} f(p, q) = \sum_{r \in T(q, \cdot)} f(q, r) \right) \quad (1)$$



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Theorem (Euler's theorem for digraphs)

There is an  $s$ - $t$  path iff there is a valuation of the  $f_i$  such that

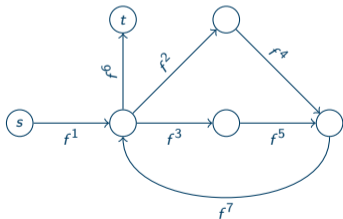
- ▶ the subgraph induced by the support and  $\{(t, s)\}$  are strongly connected,
- ▶ it satisfies (1) and  $\sum_{p \in T(\cdot, s)} f(p, s) - \sum_{r \in T(s, \cdot)} f(s, r) = 1$ .



## From paths to runs

### A formula per subgraph

Now  $\varphi_{\text{flow}}(\mathbf{f})$  is a disjunction of the **flow constraints** over all subgraphs which satisfy the support condition.



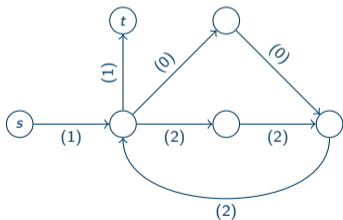




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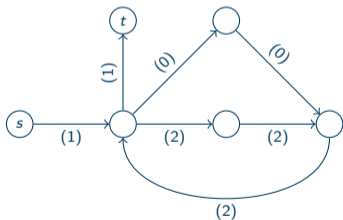




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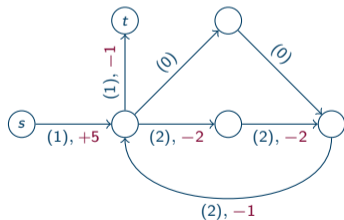




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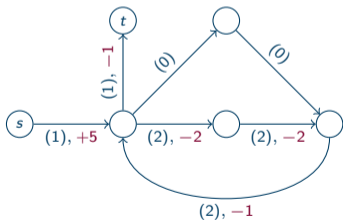
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### A path is not a run

Not every path can be **lifted** to a run because:

- ▶ of equality tests,
- ▶ the lower-bound tests,
- ▶ **the counter value cannot go negative**





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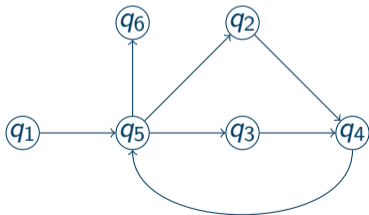
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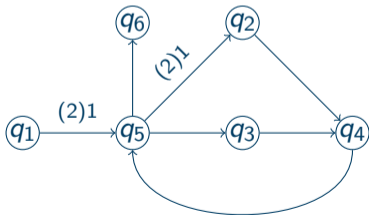




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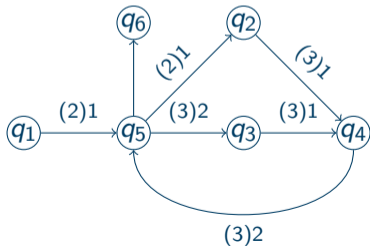




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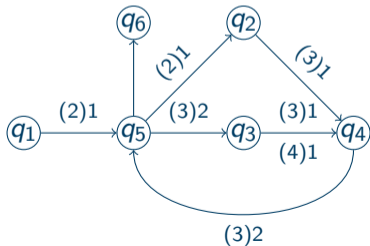




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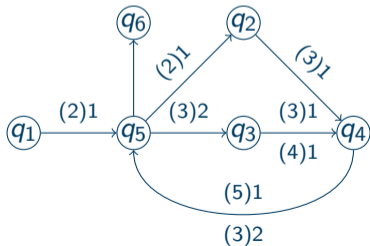




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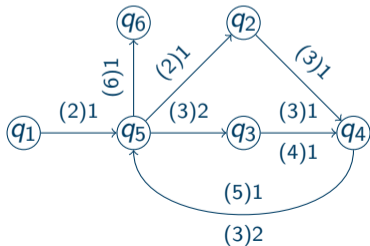




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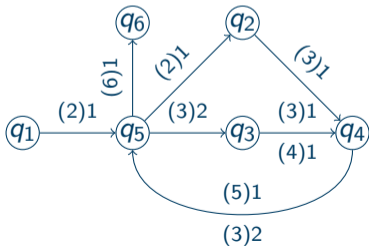




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### type 1: No positive cycles

To check the path can be lifted to a run:

$$\bigwedge_{m=1}^{|Q|} \sum_{i=1}^m \sum_{t \in T} f_i(t) \delta(t) \geq 0$$



## Weight formulas using divisibility

A formula per case (1, 2, 3)

Now  $\varphi_{\text{weight}}(\mathbf{x}, \mathbf{f})$  is a disjunction of the **weight constraints** over all decompositions.

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Divisibility to the rescue

Replace  $fx$  with a **product variable**  $z_{fx}$ :

$$(x_i \mid z_{f_i x_i}) \wedge (x_i > 0 \leftrightarrow z_{f_i x_i} > 0) \wedge \left( \sum z_{f_i x_i} \geq 0 \right)$$





## A formula per case

For each case, we get formulas like the following:

$$\varphi(\mathbf{x}) \equiv \exists z_1 z_2 \cdots \bigvee_{\substack{\text{subgraphs } i \in I \\ \text{decomp}}} \bigwedge (g_i(\mathbf{x}) \mid h_i(\mathbf{z})) \wedge \varphi_{\text{npos}}(\mathbf{x}) \wedge \mathbf{x}, \mathbf{z} \geq \mathbf{0}$$



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## The safety synthesis problem

- ▶ Positive answer if  $\forall \mathbf{x}.\Phi(\mathbf{x})$  is false
- ▶  $\forall \mathbf{x}.\Phi(\mathbf{x})$  is a sentence in  $\forall\exists_R\text{PAD}^+$



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Claim (Bozga-Iosif'05, Lechner'15)

The synthesis problems for SOCAP are decidable via an encoding into  $\forall\exists_R\text{PAD}^+$ .



## $\forall\exists_R$ PAD & Undecidability

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▶  $\forall\exists_R\text{PAD} = \forall x_1 \dots \forall x_n \exists y_1 \dots \exists y_m. \varphi(\mathbf{x}, \mathbf{z})$  with divisibilities  $f(\mathbf{x}) \mid g(\mathbf{x}, \mathbf{y})$



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*Idea.* Quantifier elimination (Generalized Chinese Remainder Theorem!) - Similar idea to Bozga & Iosif's work!



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### Theorem (Generalized CRT)

Let  $m_i \in \mathbb{N}_{>0}$ ,  $a_i, r_i \in \mathbb{Z}$  for  $1 \leq i \leq n$ . Then,

$$\exists x \in \mathbb{Z}, \bigwedge_{i=1}^n m_i \mid (a_i x - r_i) \Leftrightarrow \bigwedge_{1 \leq i, j \leq n} \gcd(a_i m_j, a_j m_i) \mid (a_i r_j - a_j r_i) \wedge \bigwedge_{i=1}^n \gcd(a_i, m_i) \mid r_i$$

The solution for  $x$  is unique modulo  $\text{LCM}(m'_1, \dots, m'_n)$ , where  $m'_i = \frac{m_i}{\gcd(a_i, m_i)}$ .



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Example:

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$\forall$ PAD!



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  - ▶ Idea. Reduction to Alternating 2-way automata (using idea from Bollig et.al'19)



## Conclusion

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Lower bound	<b>PSPACE</b> -hard	<b>coNP</b> -hard	—	<b>NP<sup>NP</sup></b> -hard	—
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Thank you for your attention!